## 14. Hand Control

This application macro is intended to be used at the commissioning with **Spin the Motor assistant** where all the analog and digital inputs are disabled as default.

Drive is started with the HAND button and giving the speed reference with the arrow buttons.

**Note!** Starting operation in AUTO mode requires configuring the I/O with parameters or the assistant or selecting another macro (recommended).

## **Hand Control**

	1	SCR	Signal ca	ble shield (screen)
	2	Al1	Not used	
	3	AGND	Analog input circuit common	
	4	10 V	Reference voltage 10 VDC	
	5	Al2	Not used	
	6	AGND	Analog input circuit common	
	7	AO1	Output frequency: 0(4)20 mA	
	8	AO2	Output current: 0(4)20 mA	
	9	AGND	Analog output circuit common	
	10	24 V	Auxiliary voltage output + 24 VDC	
	11	GND	Common for DI return signals	
	12	DCOM	Digital input common for all	
	13	DI1	Not used	
	14	DI2	Not used	
	15	DI3	Not used	
	16	DI4	Not used	
	17	DI5	Not used	
	18	DI6	Not used	
		5010	, 1	Delay autout 1 (Day 1401)
	19	RO1C		Relay output 1 (Par 1401)
	20	RO1A		Default operation
	21	RO1B		Ready=> 19 connected to 21
	22	RO2C		Relay output 2 (Par 1402)
	23	RO2A	H_	Default operation
	24	RO2B	L –	Running=> 22 connected to 24
	25	RO3C		Relay output 3 (Par 1403)
	26	RO3A	H_	Default operation
	27	RO3B	$\vdash$	Fault(-1)=> 25 connected to 27
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**Note!** Drive starts only if possible protection functions (Run enable or Start enable 1 and 2) are activated from I/O or disabled with parameters.